

SERVO-TOP

QE5542

CE

Minerva

M40SE

Instruction Manual

Part 3

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Contents

Page

Part 3

11.	Survey and List of Parameters	11.1 - 11.8
11.1	Explanation of Parameter Survey	
11.2	Explanation of Parameter List	
11.3	Parameter Survey - P40SE	
11.4	List of Parameters - P40SE	
12.	Electrical Connections Diagram P40SE	12.1 - 12.3
13.	Maintenance and Repair	13.1

Technical updatings reserved !

11. Survey and List of Parameters

11.1 Explanation of Parameter Survey

The parameter survey is designed as an aid for finding parameters quickly. It is a summary of references for the parameter list. Listed behind each reference are all parameters which exert an influence on the function described by the reference.

The parameter survey is divided into five columns:

Column 1 shows the references (functions) to which parameters are assigned.

Column 2 shows the abbreviations of the respective functions.

Column 3 shows all parameters (setting numbers) belonging to the respective reference.

Column 4 shows, for each function (reference) which controls inputs or outputs, the applicable indications such as Ex or Ax which can also be found on the connections diagram.

Column 5 shows, for each function (control inputs (Ex) or control outputs (Ax)), the respective plugs with the number of contacts (see connections diagram).

Example for searching a parameter:

Keyword (function): inverse rotation

The parameter survey shows in column 3 the parameter numbers 618, 623, 801.

Suppose that the inverse rotation function is to be enabled. The parameter list shows this function under parameter number 618.

11.2 Explanation of Parameter List

The parameter list is divided into 5 columns. These comprise, in

column 1: the parameter number,

column 2: is the explanation (meaning) of the parameters and the coding system of row 1 of the keys of the mini operator's panel, used when the parameter concerned can be programmed with the mini operator's panel,

column 3: the programming level (A, B, C) on which the parameter in question can be accessed,

column 4: the range of values within which the parameter in question can be set,

column 5: the value of the parameter in question is set on delivery ex factory.

Parameters having "either/or" validity (software switches) can merely be set to value I or II. In the case of such parameters, column 4 is empty.

Parameter numbers in acute brackets; e.g. <105>, mean the value (content) set for the parameter in question.

Example:

107 Speed for front backtack when <106> = I

I limited by <105>

II limited by <607>

Explanation:

Parameter 107 is valid only the the value (content) of parameter <106> = I.

If parameter 107 is set to I (<107> = I), then the speed for the front backtack is limited by parameter 105, e.g. <105> = 1500. If parameter 107 is set to II (<107> = II), then the speed for the front backtack is limited by the value of parameter 607, e.g. <607> = 4000.

11.3 Parameter survey M40SE (2A_K04_3.ENO)

Function	Abbrev'n	Parameter	Input Output	Connection Socket/Contacts
Backtack	RIE	523/584		
Backtack inversion	RIV	419/617	E3	X1:3
Backtack suppression	RIUNT	419		
Blower	BLA	668		
Catcher	FANG	707		
Control	REG	884/885/886 887/889/890 891/894		
Decorative backtack	ZRIE	505/506/507 508/522/523 530/775		
Direction finder position	PEIPO	653/789		
Direction of rotation	DRR	800		
End backtack	ER	108/109/110 149/604/731 732/740		
Feed reverse	TUM	721/731	E1 A5	X5:3 X4:4
Front backtack	AR	102/103/104 105/106/107 148/739		
Hardware test	HWT	797		
Inverse rotation	RDR	618/623/801		
Machine class	MAKL	799		
Needle position	NAPO	522/700/701 702/703/707 710		
Needle position change-over	NPW	616	E2	X1:1
Needle up without trimming	NHOS	616/710	E2	X1:1
Photocell	LS	111/112/113 199/615		
Presser foot	PF	554/624/651 719/729/730	E4 A4	X4:3 X4:5
Program	PR	114/206/221 304/313/554 851		

Programming level C	EBC	798		
Residual brake	STBR	718		
Safety switch no run	ANLSP	624/665		
Seam end	NE	114/206		
Single stitch	EST	617	E3	X1:3
Soft start	SANL	116/117		
Speed	DRZ	105/106/107 110/117/199 221/530/605 606/607/608 609/676/850 901		
Speed decrease	DRZAB	723/851		
Speed increase	DRZAN	722		
Speed limitation	DB	221		
Start	START	113/603		
Start delay	STVERZ	729		
Stop	STOP	114/624/665	E4	X4:3
Stop time	STOPZ	775		
Thread tension release	FSL	707	A1	X6:4
Thread trimming	SN	601/604/609 732/761/901		
Thread wiper	WI	668/715	A3	X3:5
Timing output	TA	719/721		

11.4 List of Parameters M40SE (2A_K04_3.EN)

No.	Function (Meaning)	Level	Range of Values	Standard Value
102	(AR) Front backtack stitches forward (10000000)		0-9	3
103	(AR) Front backtack stitches backward (01000000)		0-9	3
104	(AR) Front backtack correction (delayed disabling of feed reverse)	B	0-16	8
105	(AR/DRZ) Speed for front backtack (11000000)	B	100-6400	1200
106	(AR/DRZ) Speed for front backtack I variable (treadle-controlled) II constant (corresponding to <105>)	B		II
107	(AR/DRZ) Speed for front backtack when <106> = I I limited by <105> II limited by <607>	B		II
108	(ER) End backtack stitches backward (00100000)		0-9	3
109	(ER) End backtack stitches forward (10100000)		0-9	3
110	(ER/DRZ) Speed for end backtack (01100000)	B	100-6400	1200
111	(LS) Photocell compensation stitches (number of stitches from photocell clear to seam end)	A,B	1-255	6
112	(LS) Number of stitches for photocell fade-out on knit fabrics (number of stitches, according to stitch size)	A,B	0-255	0
113	(LS/START) Start with photocell I when photocell is dark only II also when photocell is clear	B		II
114	(PR/STOP/NE) Stop before seam end after stitch count (last seam section) I yes II no	B		II
116	(SANL) Soft start stitches (11100000)	A,B	0-255	0
117	(SANL/DRZ) Speed for soft start stitches (00010000)	B	30-640	400
148	(AR) Front backtack I double II single	A,B		I
149	(ER) End backtack I double II single	A,B		I
199	(DRZ/LS) Speed for photocell compensation stitches	B	300-6400	1200

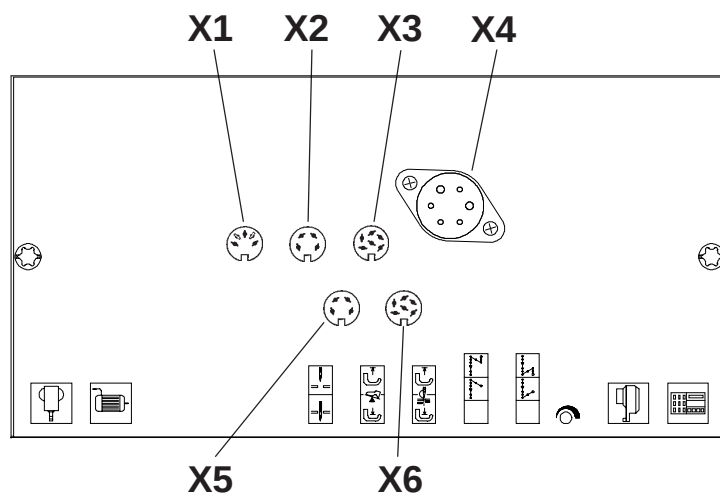
206	(NE/PR) Interrupt/discontinue seam sections at speed = constant (<203> = II) I with treadle -2 II with treadle 0	B		II
221	(PR/DB/DRZ) Speed limitation for sewing programs (or sewing program 1)	B	300-6400	1200
304	(PR) Stitch compensation at feed reverse for a seam section	B	0-2550	30
313	(PR) Programs are backtack programs (darning programs) I yes II no	B		II
419	(RIV/RIUNT) Function of external key (on operator panel B2) I backtack inversion II backtack suppression (flip-flop function)	B		I
505	(ZRIE) Number of stitches for front decorative backtack forward (stitch in stitch) (speed = <530>) (10010000)		0-9	3
506	(ZRIE) Number of stitches for front decorative backtack backward (stitch in stitch) (speed = <530>) (01010000)		0-9	3
507	(ZRIE) Number of stitches for end decorative backtack backward (stitch in stitch) (speed = <530>) (11010000)		0-9	3
508	(ZRIE) Number of stitches for end decorative backtack forward (stitch in stitch) (speed = <530>) (00110000)		0-9	3
522	(NAPO/ZRIE) Needle position when stop occurs during decorative backtack (stitch in stitch) I position 2 (up) II position 1 (down) (10110000)	B		II
523	(RIE/ZRIE) Backtack I decorative backtack (stitch in stitch) II standard backtack (01110000)	A,B		II
530	(DRZ/ZRIE) Speed (max.) for decorative backtack (11110000)	B	100-6400	1000
554	(PF/PR) Presser foot position after seam section stitch count and treadle position > +1 I up II down	B		I
584	(RIE) Backtack I four times II double	B		II

601	(SN) Trimming I yes II no (00001000)	B		I
603	(START) Start after seam end I after treadle 0 only II immediate start of operation	B		I
604	(SN/ER) Trimming after single end backtack I forward II backward	B		I
605	(DRZ) Actual speed in display I yes II no	B		II
606	(DRZ) Speed: level 1 (min.) (10001000)	B	30-640	180
607	(DRZ) Speed: level 12 (max.) (01001000)	B	100-10000	1200
608	(DRZ) Speed level curve (treadle characteristic) I linear II not linear	B		I
609	(SN/DRZ) Trimming speed 1 (11001000)	B	30-300	180
615	(LS) End recognition when photocell goes I from light to dark II from dark to light	B		II
616	(NPW/NHOS) Function of external key (input E2) I needle position change-over (NPW) II needle up without trimming (NHOS)	B		II
617	(EST/RIV) Function of external key (input E3) I single stitch (EST) II backtack function inverted (RIV)	B		I
618	(RDR) Inverse rotation after seam end I yes II no (00101000)	B		II
623	(RDR) Delay in start-up time (ms) for inverse rotation	B	0-2550	10
624	(ANLSP/STOP/PF) Function of external key (input E4) I stop/safety switch no run II presser foot	B		II
651	(PF) Presser foot with automatic descent on machine stop I yes II no	B		I
653	(PEIPO) Direction finder position before sewing I yes II no	B		II
665	(ANLSP/STOP) Run locking/stop I contact closed II contact open	C		I

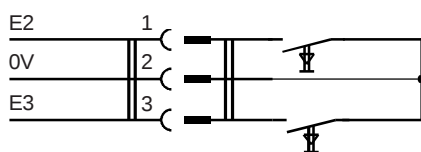
668	(BLA/WI) Thread wiper/thread clearer I yes II no (10101000)	B		I
676	(DRZ) Speed adjustment via potentiometer possible I yes II no	B		I
700	(NAPO) Needle position 0 (reference position of the needle) (01101000)	B	0-239	0
701	(NAPO) Angular adjustment I with handwheel (teach-in) II by keys (+/-)	B		I
702	(NAPO) Needle position 1 (needle down) (11101000)	B	0-239	75
703	(NAPO) Needle position 2 (thread take-up lever up) (00011000)	B	0-239	213
707	(NAPO/FSL/FANG) Needle position 9 (thread tension release or thread catcher start) (00100000)	B	0-239	119
710	(NAPO/NHOS) Needle position 3 (needle up) (11011000)	B	0-239	200
715	(WI) Duration (ms) of thread wiper	B	0-2550	120
718	(STBR) Timing of residual brake (0 = brake off) (00111000)	B	0-100	0
719	(PF/TA) Timing output A4 (0 = 100% switching on)	B	0-100	40
721	(TUM/TA) Timing output A5 (0 = 100% switching on)	B	0-100	40
722	(DRZAN) Acceleration ramp 1 gradual 50 steep	B	1-50	40
723	(DRZAB) Brake ramp 1 gradual 50 steep	B	1-50	31
729	(STVERZ/PF) Start delay after lowering presser foot	B	0-2550	120
730	(PF) Lift delay for presser foot after seam end	B	0-2550	50
731	(TUM/ER) Time required to correct feed reverse at end backtack	B	0-2550	40
732	(SN/ER) Delay (ms) for trimming after single end backtack	B	0-2550	30
739	(AR) Delay (ms) for speed after front backtack	B	0-2550	120
740	(ER) Delay before stitch counting for end backtack	B	0-2550	0
761	(SN) Extension of thread trimming after positioning	B	0-2550	0
775	(ZRIE/STOPZ) Stop time (ms) with stitch in stitch backtack (decorative backtack)	B	0-2550	100
789	(PEIPO) Angle for direction finder position	B	0-239	225
797	(HWT) Hardware test	B		II

798	(EBC) Programming level C I yes II no	B		II
799	(MAKL) Machine class which has been selected (10111000)	B	1-1	1
800	(DRR) Direction of motor rotation viewed from belt pulley I left-hand rotation II right-hand rotation (01111000)	B		II
801	(RDR) Reverse rotation angle after seam end	B	5-200	30
850	(DRZ) Maximum motor speed	C	2000-6000	4500
851	(PR/DRZAB) Brake ramp for stitch-count seams I steep II gradual	C		I
884	(REG) Proportional amplification of the speed control (in general)	B	4-50	12
885	(REG) Integral amplification of the speed control	C	0-100	30
886	(REG) Proportional amplification of the order controllers	C	1-50	20
887	(REG) Differential amplification of the order controllers	C	1-100	30
889	(REG) Time required for order controlling (0 = always)	C	0-1000	400
890	(REG) Proportional amplification of the superior order controllers for the residual brake	C	1-50	25
891	(REG) Proportional amplification of the lower speed controllers for the residual brake	C	1-50	20
894	(REG) Rotational direction of synchronizer during sewing operation (self teaching) I right-hand rotation II left-hand rotation	C		I
897	(SONST) Commutation transmitter I ABB II QR	C		II
898	(SONST) Number of motor poles I 4 poles II 6 poles	C		II
901	(DRZ/SN) Trimming release speed	C	30-500	300

12. Anschlußplan der Steckerplatte M40SE

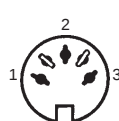


X1

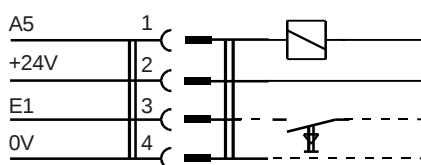


S2

S3



X2

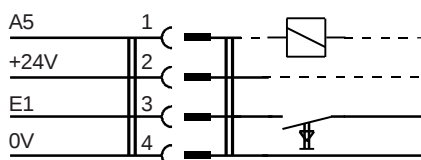


Y5

S1



X5

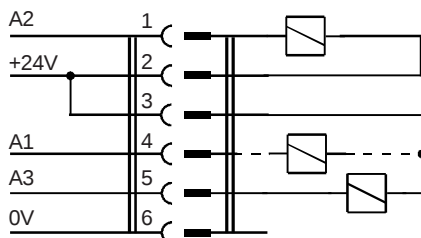


Y5

S1



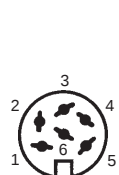
X3



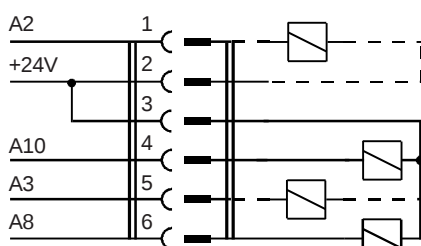
Y2

Y1

Y3



X6

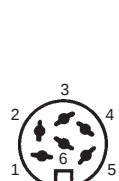


Y2

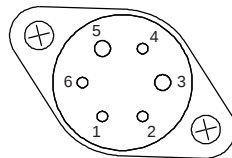
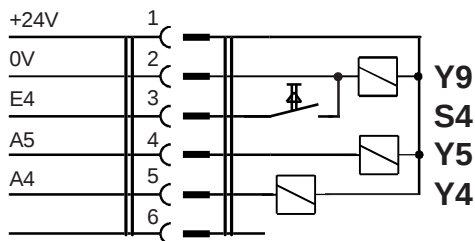
Y1

Y3

Y8



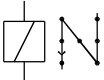
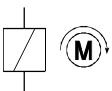
X4



Bedeutung der Magnete bzw. Magnetventile, Taster / Meaning of magnets and/or solenoids and keys
 Signification des aimants resp. solenoides et touches / Significação dos ímãs e/ou as solenoidas e teclas
 Significato dei magneti, delle valvole magnetiche e dei tasti / Significación de los imanes y/o los solenoides
 y pulsadores / Betekenis van de magneten resp. magneetkleppen, toetsen

S1		Transportumstellung von Hand / manual feed reverse / renversement de marche manuel / mudança do transporte manual / commutazione trasporto a mano / inversión de transporte manual / handmatige transportomschakeling
S2		<616> = I: Nadelpositionswechsel / needle position change-over / changement de position d'aiguille / troca de posição da agulha / cambio di posizione dell'ago / cambio de posición de aguja / naaldpositie-verwisseling
S2		<616> = II: Nadel hoch ohne Schneiden / needle up without thread trimming / aiguille en haut sans coupe / agulha para cima sem corte de linhas / ago su senza taglio / aguja arriba sin corte / naald omhoog zonder snijden
S3		<617> = I: Einzelstich / single stitch / point unique / ponto individual / punto singolo / puntada individual / enkele steek
S3		<617> = II: Nachfolgende Riegelfunktion invertieren / invert subsequent backtack function / inverser la prochaine fonction de bridage / inverter o próximo remate / invertire la funzione d'affr. successiva / invertir la próxima función de remate / inverteren op elkaar volgende hechtfunctie
S4		<624> = I: STOP
S4		<624> = II: Presserfuß heben / lifting presser foot / relevage du pied presseur / levantar do calcador / sollevamento del alzapiedino / elevación de prensatelas / drukvoet optillen
Y1 I max 8 A *		Fadenentspanner / thread tension release / détenteur de fil / soltar tensão da linha / sbloccaggio tendifilo / detensión del hilo / verbreken van de draadspanning
Y2 I max 8 A *		Fadenschneider / thread trimmer / coupe-fil / corte de linhas / rasafilo / cortahilos / draadsnijder
Y3 I max 8 A *		Fadenwischer / thread wiper / écarteur de fil / retira-linhas / scartafilo / retirahilos / draadwisser
Y4 I max 8 A *		Presserfuß heben / lifting presser foot / relevage du pied presseur / levantar do calcador / sollevamento del alzapiedino / elevación de prensatelas / drukvoet optillen

Bedeutung der Magnete bzw. Magnetventile, Taster / Meaning of magnets and/or solenoids and keys
 Signification des aimants resp. solenoides et touches / Significação dos ímãs e/ou as solenoidas e teclas
 Significato dei magneti, delle valvole magnetiche e dei tasti / Significación de los imanes y/o los solenoides
 y pulsadores / Betekenis van de magneten resp. magneetkleppen, toetsen

Y5 I max 8 A *		Transportumsteller / feed reverse / renversement de marche / mudança do transporte / commutazione trasporto / inversión de transporte / transportomschakeling
Y8 I max 300 mA		Maschinenlauf / motor runs / moteur en marche / motor em movimento / motore in moto / motor en marcha / loop van de machine
Y9		Hauptventil / master valve / valve principale / válvula principal / valvola principale / válvula principal / hoofdventiel

Q Die Summe der Lastströme aller gleichzeitig eingeschalteten Stellglieder (Magnete, Magnetventile) darf den Wert von 4A nicht überschreiten (siehe hierzu Kapitel 2. Technische Daten).

The total of load currents of all servos activated simultaneously (solenoids, solenoid valves) is not allowed to exceed 4 amps (see also section 2. Technical Specifications).

Le total des courants de charge de tous les vérins (aimants, électro-vannes) activés simultanément ne doit pas dépasser 4 A (voir aussi le chapitre 2. "caractéristiques techniques").

A soma das correntes sob carga de todos os atuadores ligados ao mesmo tempo (ímãs, solenóides) não pode ultrapassar o valor de 4A (ver também capítulo 2. Dados Técnicos).

La somma delle correnti di carico di tutti gli attuatori inseriti contemporaneamente (magnetici, elettrovalvole) non deve essere superiore a 4 A (vedere il capitolo 2. Dati Tecnici).

La suma de las corrientes bajo carga de todos los elementos de todos los componentes de regulación conectados simultáneamente (imanes, válvula magnética) no podrá sobrepasar el valor de 4A (véase también el capítulo 2. de datos técnicos).

De belastingsstroom van alle tegelijkertijd ingeschakelde bedieningsschakels (magneten, magneetventielen) mag in totaal niet meer dan 4 A bedragen (zie hiervoor hoofdstuk 2. Technische gegevens).

13. Maintenance and Repair



!! Before starting maintenance or repair work, switch off the SERVO-TOP, separate the drive system from mains power (for instance by pulling out the mains plug) and wait for the motor to come to a complete stop.

General maintenance work must only be done by specially trained personnel paying close attention to the operating instructions.

The SERVO-TOP is largely maintenance-free.

However, make sure to perform the following maintenance work:

Depending on the operating conditions, clean the drive system regularly, at least once a week, from any dust or lint. Make sure in particular that the ventilation louvres and cooling fins of the motor, especially the cooling fins between the motor and the control box, are perfectly clean (Fig. 13).

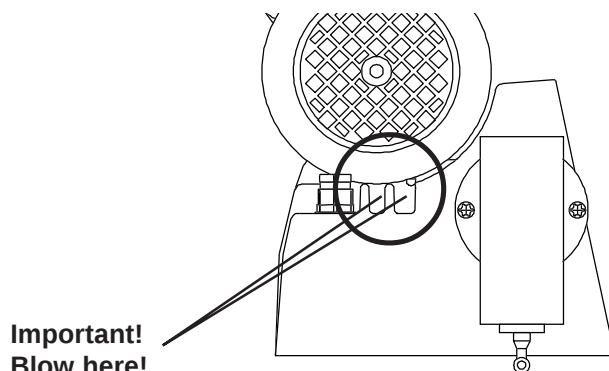


Fig. 13

Remove any threads caught on the synchronizer shaft or on the belt pulley and/or motor shaft.

Check if the drive system is perfectly secured to the stand and that the accessories (synchronizer on machine shaft, speed control unit on control box) are safely mounted in their respective positions.

Check the drive belt for any wear and for correct tension.
Incorrect belt tension can increase noise and vibrations.



When opening covers or removing parts, apart from those removable by hand, live elements can be exposed.
Connections can also be electrically live.

If you require to open the drive system before starting maintenance or repair work or before replacing any parts, disconnect the drive system from any and all power sources.

If maintenance or repair work on the open unit is unavoidable, this may only be done by qualified personnel familiar with the risks involved. Observe all regulations as per EN 50110.

There can still be capacitors carrying a charge in the power electronics system, even when the drive system has been disconnected from all power sources. To avoid injury by electrical shock, it is therefore essential to wait at least 10 minutes between mains power shutoff and opening the control box.

In order to protect semi-conductor components from overvoltage, use only high-resistivity measuring equipment when making checks on the control system.

Any repair or servicing work requiring skilled knowhow may only be done by qualified personnel authorized by Quick-Rotan.

We emphasize that in accordance with the product liability law we are under no responsibility for damages caused by our products if these are due to

- unqualified repair
- the use of components not authorized by us
- actions made by any persons not authorized by us.

www.promelectroavtomat.ru